

# Lifts and generalized morphisms

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joint work with  
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# Overview

1

## The computability of $R - \mathbf{fpmod}$

- Axioms of an ABELian category (reminder)
- Basic matrix operations and computability of  $R - \mathbf{fpmod}$

2

## Generalized morphisms

- Generalized morphisms
- Spectral sequences of filtered complexes

# Computable ring

## Definition ([BLH11, Def. 3.2])

A ring  $R$  is called left (resp. right) **computable** if one can specify an algorithm to solve inhomogeneous linear equations  $B = XA$  (resp.  $B = AX$ ) over  $R$ .

In other words, we want to be able to compute a generating set of syzygies and to effectively decide solvability, i.e., to compute a particular solution.

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# Computable ABELian categories

## Definition ([BLH11, Def. 2.1])

An ABELian category is called **computable**<sup>a</sup> if the existential quantifiers entering the defining axioms can be turned into constructive ones.

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<sup>a</sup>as an ABELian category.

# $R - \text{fpmod}$ over a computable ring is computable

## Theorem ([BLH11, Thm. 3.4])

*The category  $R - \text{fpmod}$  of finitely presented left (resp. right) modules over a left (resp. right) computable ring  $R$  is ABELian and, as such, computable.*

Below we list the two additional axioms an additive category needs to satisfy to become ABELian.

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# $\mathcal{A}$ is an ABELian category

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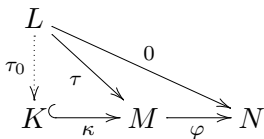
- ⑩ For any morphism  $\varphi : M \rightarrow N$  there **exists** a **kernel**  $\ker \varphi \xrightarrow{\kappa} M$ , such that
- ⑪ for any morphism  $\tau : L \rightarrow M$  and any monomorphism  $\kappa : K \hookrightarrow M$  with  $\tau\varphi = 0$  for  $\varphi = \text{coker } \kappa$  there **exists** a **lift**  $\tau_0 : L \rightarrow K$  of  $\tau$  along  $\kappa$ .
- ⑫ For any morphism  $\varphi : M \rightarrow N$  there **exists** a **cokernel**  $N \xrightarrow{\varepsilon} \text{coker } \varphi$ , such that
- ⑬ for any morphism  $\eta : N \rightarrow L$  and any epimorphism  $\varepsilon : N \twoheadrightarrow C$  with  $\varphi\eta = 0$  for  $\varphi = \ker \varepsilon$  there **exists** a **colift**  $\eta_0 : C \rightarrow L$  of  $\eta$  along  $\varepsilon$ .



A morphism  $\kappa : K \rightarrow M$  is called “the” **kernel** of  $\varphi : M \rightarrow N$  if

- (i)  $\kappa\varphi = 0$ , and
- (ii) for all objects  $L$  and all morphisms  $\tau : L \rightarrow M$  with  $\tau\varphi = 0$  there **exists** a *unique* morphism  $\tau_0 : L \rightarrow K$ , such that  $\tau = \tau_0\kappa$ .  $\tau_0$  is called the **lift** of  $\tau$  along  $\kappa$ .

It follows from the uniqueness of the lift  $\tau_0$  that  $\kappa$  is a *monomorphism*.



$K$  is called “the” **kernel object** of  $\varphi$ . This funny diagram just means that

$$\text{im } \tau \leq \text{im } \kappa,$$

in the categorial language.

# $X = \text{SyzygiesGenerators}(A)$

Let  $A$  be an  $r_1 \times r_0$ -matrix over  $R$ .

We call  $X \in R^{r_2 \times r_1}$  a matrix of **generating syzygies (of the rows) of  $A$**  if for all  $x \in R^{1 \times r_1}$  with  $xA = 0$ , there exists a  $y \in R^{1 \times r_2}$  such that  $yX = x$ . The rows of  $X$  are thus a generating set of the kernel of the map  $R^{1 \times r_1} \xrightarrow{A} R^{1 \times r_0}$ . We write

$$X = \text{SyzygiesGenerators}(A)$$

and say that  $X$  is the most general solution of the homogeneous linear system  $XA = 0$ .

# $X = \text{RelativeSyzygiesGenerators}(A, L)$

Further let  $L$  be an  $r'_1 \times r_0$ -matrix over  $R$ . We call  $X \in R^{r_2 \times r_1}$  a matrix of **relative generating syzygies (of the rows) of  $A$  modulo  $L$**  if the rows of  $X$  form a generating set of the kernel of the map  $R^{1 \times r_1} \xrightarrow{A} \text{coker } L$ . We write

$$X = \text{RelativeSyzygiesGenerators}(A, L)$$

and say that  $X$  is the most general solution of the homogeneous linear system  $XA + YL = 0$ . This last system is of course equivalent<sup>1</sup> to solving the homogeneous linear system

$$\begin{pmatrix} X & Y \end{pmatrix} \begin{pmatrix} A \\ L \end{pmatrix} = 0.$$

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<sup>1</sup>In practice, however, one can often implement efficient algorithms to compute  $X$  without explicitly computing  $Y$ .

# How to compute $\ker \varphi \xrightarrow{\kappa} M$ of $\varphi : M \rightarrow N$ ?

In the following we take  $M := \text{coker } M$  and  $N := \text{coker } N$ .

## How to compute $\ker \varphi \xrightarrow{\kappa} M$ of $\varphi : M \rightarrow N$ ?

To compute the kernel  $\ker \varphi \xrightarrow{\kappa} M$  of a morphism  $\varphi : M \rightarrow N$  represented by a matrix  $A$  we do the following:

- 1 First compute

$$X = \text{RelativeSyzygiesGenerators}(A, N),$$

the matrix representing  $\kappa$ .

- 2 Then  $\ker \varphi$  is presented by the matrix

$$K = \text{RelativeSyzygiesGenerators}(X, M).$$

$$X = \text{RightDivide}(B, A)$$

Further let  $B$  be an  $r_2 \times r_0$ -matrix over  $R$ .

Deciding the solvability and solving the inhomogeneous linear system  $XA = B$  is equivalent to the construction of matrices  $N, T$  such that  $N = TA + B$  satisfying the following condition: If the  $i$ -th row of  $B$  is a linear combination of the rows of  $A$ , then the  $i$ -th row of  $N$  is zero<sup>2</sup>. Hence the inhomogeneous linear system  $XA = B$  is solvable (with  $X = -T$ ), if and only if  $N = 0$ . We write

$$(N, T) = \text{DecideZeroEffectively}(A, B) \text{ and } N = \text{DecideZero}(A, B).$$

In case  $N = 0$  we write

$$X = \text{RightDivide}(B, A).$$

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<sup>2</sup>So we do not require a “normal form”, but only a mechanism to decide if a row is zero modulo some relations.

# submodule membership problem

Rows of the matrices  $A$  and  $B$  can be considered as elements of the free module  $R^{1 \times r_0}$ .

- Deciding the solvability of the inhomogeneous linear system  $XA = B$  for a single row matrix  $B$  is thus nothing but the **submodule membership problem** for the submodule generated by the rows of the matrix  $A$ .
- Finding a particular solution  $X$  (in case one exists) solves the submodule membership problem **effectively**.

$$X = \text{RightDivide}(B, A, L)$$

As with relative syzygies we also consider a relative version. In case the inhomogeneous system  $XA = B \pmod L$  is solvable, we denote a particular solution by

$$X = \text{RightDivide}(B, A, L).$$

This is equivalent to solving

$$\begin{pmatrix} X & Y \end{pmatrix} \begin{pmatrix} A \\ L \end{pmatrix} = B.$$

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11 for any morphism  $\tau : L \rightarrow M$  and any monomorphism  $\kappa : K \hookrightarrow M$  with  $\tau\varphi = 0$  for  $\varphi = \text{coker } \kappa$  there **exists** a **lift**  $\tau_0 : L \rightarrow K$  of  $\tau$  along  $\kappa$ .
- 12 For any morphism  $\varphi : M \rightarrow N$  there **exists** a **cokernel**  $N \xrightarrow{\varepsilon} \text{coker } \varphi$ , such that
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# How to compute the lift $\tau_0 : L \rightarrow K$ of $\tau$ along $\kappa$ ?

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Let  $\tau : L \rightarrow M$  be a morphism represented by a matrix  $B$  and  $\kappa : K \hookrightarrow M$  a monomorphism represented by a matrix  $A$  with  $\tau\varphi = 0$  for  $\varphi = \text{coker } \kappa$ . Then the matrix

$$X = \text{RightDivide}(B, A, M)$$

is a representation matrix for  $\tau_0 : L \rightarrow K$ , the lift of  $\tau$  along  $\kappa$ .

It is an easy exercise<sup>3</sup> to check that  $X$  represents a *morphism*.

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<sup>3</sup>Cf. [BR08, 3.1.1, case (2)]).

# Applications of lifts

## Applications of the lift in ABELian categories

- Compute the morphism part of a functor, e.g.,

$$\mathrm{Ext}_R^c(N, L) \xrightarrow{\mathrm{Ext}_R^c(\varphi, L)} \mathrm{Ext}_R^c(M, L),$$

for  $\varphi : M \rightarrow N$ .

- ...

# $\mathcal{A}$ has enough projectives

$\mathcal{A}$  has **enough projectives**:

- 14 For each morphism  $\varphi : P \rightarrow N$ , with  $P$  projective, and each morphism  $\varepsilon : M \rightarrow N$  with  $\text{im } \varphi \leq \text{im } \varepsilon$  there **exists** a **projective lift**  $\varphi_1 : P \rightarrow M$  of a  $\varphi$  along  $\varepsilon$ .
- 15 For each object  $M$  there **exists** a **projective hull**  $\nu : P \twoheadrightarrow M$ .

# Projective object and projective lift

## Definition

An object  $P$  in a category  $\mathcal{A}$  is called **projective**, if for each epimorphism  $\varepsilon : M \twoheadrightarrow N$  and each morphism  $\varphi : P \rightarrow N$  there **exists** a morphism  $\varphi_1 : P \rightarrow M$  with  $\varphi_1 \varepsilon = \varphi$ .

$$\begin{array}{ccc} P & & \\ \varphi_1 \downarrow \cdots & \searrow \varphi & \\ M & \xrightarrow{\varepsilon} & N \end{array}$$

We call  $\varphi_1$  a **projective lift** of  $\varphi$  along  $\varepsilon$ .

# Deciding projectiveness in $R - \text{fpmod}$

We already know several methods to test projectiveness in  $R - \text{fpmod}$ .

- At least one of them does not make use of syzygies (needs commutativity).
- Another one uses  $\text{Ext}_R^1$  (needs commutativity).
- The FITTING criterion:  $\text{Fitt } M = R$  (needs commutativity).
- And two that do not need the commutativity assumption, but the computability of a finite free resolution instead [AB69, CQR05] and [Lam06, QR07].

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# Deciding projectiveness in $R - \mathbf{fpmod}$ using a split

Let  $\nu : F_0 \twoheadrightarrow M$  be a free presentation of the  $R$ -module  $M$ . It follows that  $M$  is projective if and only if  $\nu$  admits a section  $\sigma : M \hookrightarrow F_0$  (i.e.,  $\sigma\nu = \text{id}_M$ ).

## Deciding projectiveness in $R - \mathbf{fpmod}$ without syzygies

Finding the section  $\sigma$  for a finitely and freely presented module  $M \xleftarrow{\nu} F_0 \xleftarrow{M} F_1$  leads to solving the two-sided inhomogeneous linear system

$$X + YM = \text{Id}, \quad MX = 0,$$

over  $R$ , where  $X$  is a square matrix representing  $\sigma$  and  $Y$  another unknown matrix.

This system can be easily brought to a one-sided inhomogeneous linear system if  $R$  is commutative<sup>4</sup>.

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# Deciding projectiveness in $R - \text{fpmod}$ using $\text{Ext}_R^1$

Again let  $\nu : F_0 \twoheadrightarrow M$  be a free presentation of  $M$ .

## Theorem

*An  $R$ -module  $M$  is projective if and only if  $\text{Ext}_R^1(M, K_1(M)) = 0$ .*

## Proof.

$\text{Ext}_R^1(M, K_1(M)) = 0$  implies that the extension  $M \leftarrow F_0 \hookrightarrow K_1(M)$  splits, i.e.,  $F_0 \cong M \oplus K_1(M)$  and  $M$  is projective as a direct summand of the free module  $F_0$ . □

Computing  $\text{Ext}_R^1(M, K_1(M))$  involves computing syzygies. We again assume that  $R$  is *commutative*.

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# Deciding projectiveness in $R - \text{fpmod}$ using the FITTING criterion

## Theorem ([Eis95, Prop. 20.8])

A finitely presented  $R$ -module  $M$  over a commutative ring  $R$  is projective of **constant rank** if and only if  $\text{Fitt } M = R$ .

## Example (Caution)

Take  $R := k[x]/\langle x^2 - x \rangle \cong k \times k$  and

$$I := \langle x \rangle \cong k \oplus 0 \triangleleft R.$$

$I$ , as an  $R$ -module, is projective but not of constant rank (its (global) rank is 0).

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# Deciding freeness – QUILLEN-SUSLIN

Deciding freeness seems to be much harder than deciding projectiveness.

## Theorem (QUILLEN-SUSLIN)

*If  $R$  is a commutative principal ideal domain then  $R[x_1, \dots, x_n]$  is a HERMITE ring.*

See [FQ07] for an implementation.

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# Deciding freeness – Hairy ball theorem

## Example (Hairy ball theorem)

Let  $R = \mathbb{R}[x, y, z] / \langle x^2 + y^2 + z^2 - 1 \rangle$ . Then

$$R^{1 \times 3} / \langle (x \ y \ z) \rangle$$

is stably free but not free.

## Proof.

This follows from the hairy ball theorem in analysis. □

There is no known<sup>5</sup> *algebraic* proof for non-freeness!

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<sup>5</sup>July 2011

# Software demo



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# How to compute the **free lift** $\varphi_1 : P \rightarrow M$ ?

Let  $F$  be a **free**  $R$ -module presented by an empty matrix, i.e.,  $F$  is given on a set of *free* generators. Further let  $\varphi : F \rightarrow N$  and  $\varepsilon : M \rightarrow N$  be morphisms represented by the matrices  $B$  and  $A$ , respectively.

$$\begin{array}{ccc} F & & \\ \varphi_1 \downarrow & \searrow \varphi & \\ M & \xrightarrow{\varepsilon} & N \end{array}$$

How to compute the **free lift**  $\varphi_1 : P \rightarrow M$  of a  $\varphi$  along  $\varepsilon$ ?

The image condition  $\text{im } \varphi \leq \text{im } \varepsilon$  guarantees the existence of the matrix

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which is a matrix representing a **free lift**  $\varphi_1 : F \rightarrow M$  along  $\varepsilon$  (cf. [BR08, 3.1.1, case (1)]).

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How to compute the **free lift**  $\varphi_1 : P \rightarrow M$  of a  $\varphi$  along  $\varepsilon$ ?

The image condition  $\text{im } \varphi \leq \text{im } \varepsilon$  guarantees the existence of the matrix

$$X = \text{RightDivide}(B, A, N),$$

which is a matrix representing a **free lift**  $\varphi_1 : F \rightarrow M$  along  $\varepsilon$  (cf. [BR08, 3.1.1, case (1)]).

# Applications of free lifts

## Applications of the free lift in ABELian categories

- Resolution of morphisms.
- Horseshoe lemma and Cartan-Eilenberg resolution.
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# Overview

1

## The computability of $R - \mathbf{fpmod}$

- Axioms of an ABELian category (reminder)
- Basic matrix operations and computability of  $R - \mathbf{fpmod}$

2

## Generalized morphisms

- Generalized morphisms
- Spectral sequences of filtered complexes

# HASSE diagram of a morphism

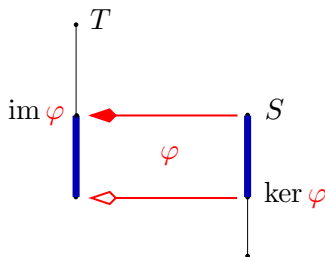


Figure: The homomorphism theorem of a morphism

# Subfactors as images?

How to relate **subfactor** objects, e.g., (co)homologies, to their hull objects in a categorical way?

# HASSE diagram of a generalized morphism

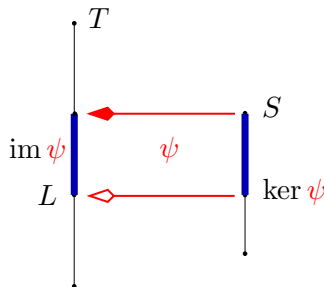


Figure: A homomorphism theorem generalized morphism

Cf. [Bar, Def. 4.1].

# HASSE diagram of a generalized morphism

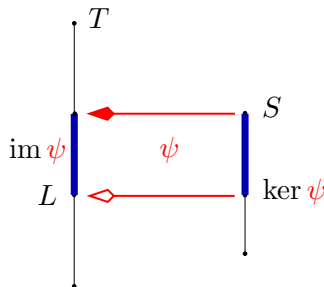


Figure: A homomorphism theorem generalized morphism

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# Composition of generalized morphisms

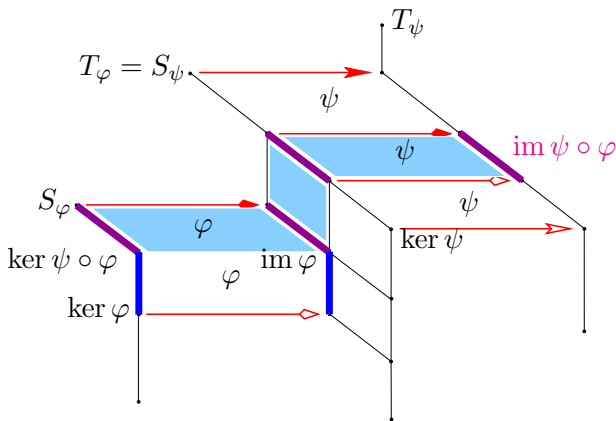


Figure: The composition  $\psi \circ \varphi$

# The lifting lemma

Lemma (The lifting lemma [Bar, Lemma 4.5])

Let  $\gamma = (\bar{\gamma}, L_\gamma)$  and  $\beta = (\bar{\beta}, L_\beta)$  be two generalized morphisms with the same target  $N$ . Suppose that  $\beta$  lifts  $\gamma$ . Then there exists a generalized morphism  $\alpha : M' \rightarrow N'$  with  $\beta \circ \alpha \triangleq \gamma$ ,

$$\begin{array}{ccc} M' & & \\ \downarrow \alpha & \searrow \gamma & \\ N' & \xrightarrow{\beta} & N. \\ & & \vdots \end{array}$$



# Lifting of generalized morphisms

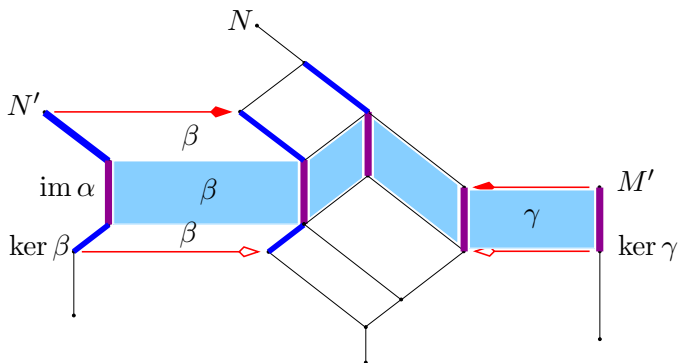
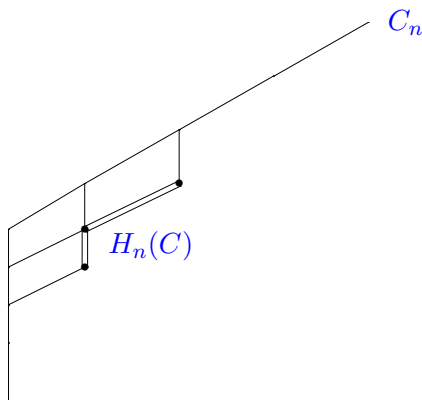


Figure: The lifting condition and the lifting lemma

# The spectral filtration of $H(C_n)$

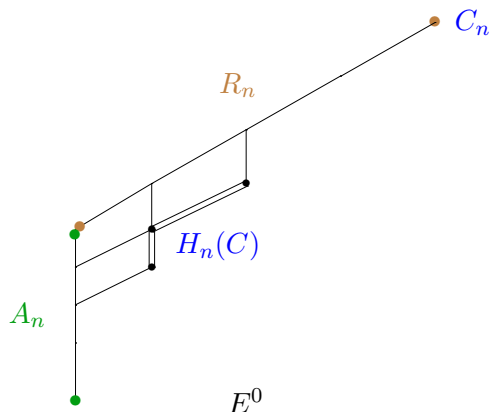
Q: What happens inside the object  $C_n$  while flipping the pages?



A:  $H_n(C)$  got approximated and the homomorphism theorem can be used to recover the extension [Bar].

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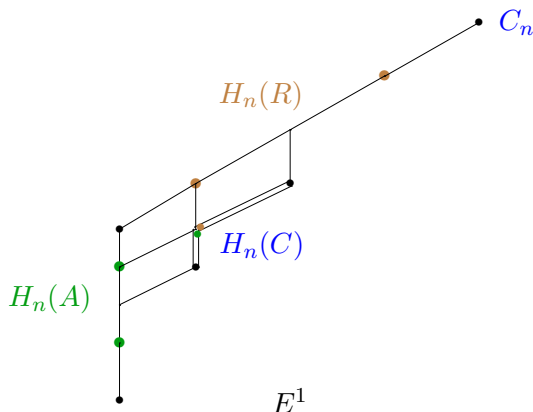
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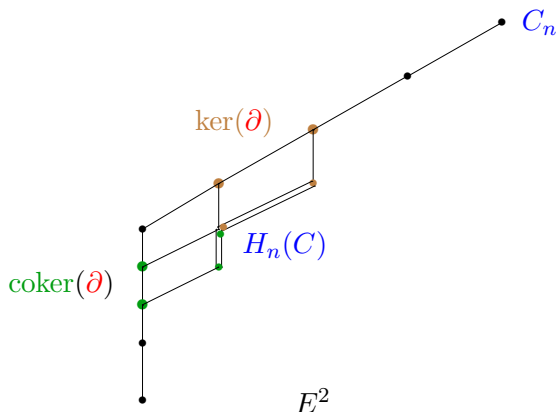
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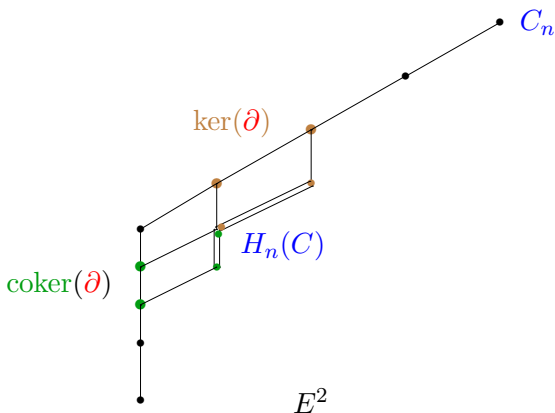
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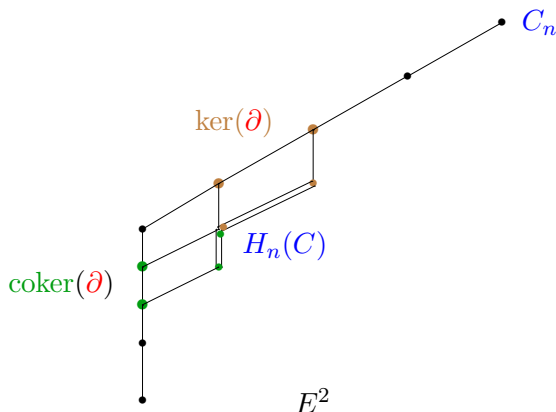
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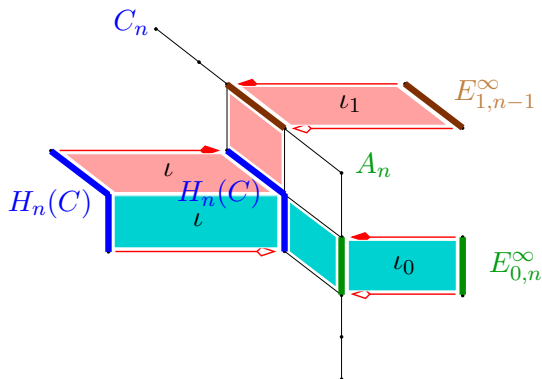


Figure:  $\iota$  lifts  $\iota_0$  and  $\iota_1$



# An $m$ -filtration

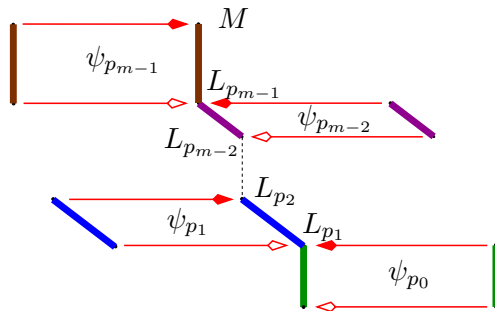


Figure: An ascending  $m$ -filtration system

# Generalized morphisms

## Generalized morphisms





- Provide a categorical substitute for the annoying diagram chasing of elements which, a priori, do not exist in general ABELian categories.
- Offer an extremely computer-friendly data structure to control the enormous amount of generalized lifting processes needed in homological algebra.

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Thank you for your attention

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