

Abelian categories and linear partial differential equations

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Overview

1 From linear systems to D -modules

- Differential consequences
- From systems to modules
- Advantages

2 Purity filtration

- Derived Categories
- The CARTAN-EILENBERG resolution
- Example

Linear systems of PDEs

Consider the CAUCHY-RIEMANN differential equation:

$$u_x - v_y = 0, \quad u_y + v_x = 0 \quad (\text{CR})$$

Q:

How can we deal with this differential equation **algebraically**?

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How can we deal with this differential equation **algebraically**?

Computing *modulo* the equations

Idea: Consider differential consequences

- $u_{xx} + u_{yy} = ?$
- $v_{xx} + v_{yy} = ?$
- $u_{xxx} + u_y + v_x + v_{yyy} = ?$
- $u_{xxx} + u_{yy} + v_{xx} + v_{yyy} = ?$
- ...

Q:

How can we consider all differential consequences simultaneously?

Computing *modulo* the equations

Idea: Consider **differential consequences**

- $u_{xx} + u_{yy} = \partial_x(u_x - v_y) + \partial_y(u_y + v_x) = 0$
- $v_{xx} + v_{yy} = -\partial_y(u_x - v_y) + \partial_x(u_y + v_x) = 0$
- $u_{xxx} + u_y + v_x + v_{yyy} = ?$
- $u_{xxx} + u_{yy} + v_{xx} + v_{yyy} = ?$
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- $u_{xx} + u_{yy} = 0$
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- $u_{xxx} + u_y + v_x + v_{yyy} = (\partial_x^2 - \partial_y^2)(u_x - v_y) + (\partial_x \partial_y + 1)(u_y + v_x) = 0$
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How can we consider all differential consequences simultaneously?

First step: From systems to differential operators

The CAUCHY-RIEMANN differential equation can be rewritten as

$$\underbrace{\begin{pmatrix} \partial_x & -\partial_y \\ \partial_y & \partial_x \end{pmatrix}}_A \underbrace{\begin{pmatrix} u \\ v \end{pmatrix}}_\psi = 0,$$

- with $A \in D^{p \times q}$ ($p = q = 2$)
- for $D = \mathbb{R}[\partial_x, \partial_y]$, or more general diff. rings $R[\partial_x, \partial_y]$
- and $\psi \in \mathcal{F}^{2 \times 1}$, for $\mathcal{F} = C^\infty(\mathbb{R}^n)$ ($n = 2$)
- The solution space:

$$\text{Sol}_{\mathcal{F}}(A) := \{\psi \in \mathcal{F}^{q \times 1} \mid A\psi = 0\}$$

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Second step: From differential operators to **modules**

- $u_{xx} + u_{yy}$



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- $\partial_x(u_x - v_y) + \partial_y(u_y + v_x)$



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computing modulo the equations

\triangleq

computing in the left D -module $M := D^{1 \times q} / D^{1 \times p} A$.

The module M

$M = D^{1 \times q} / D^{1 \times p} A$ is thus **finitely presented**:

- **Generators:** The q residue classes of standard generators of the free D -module $F_0 = D^{1 \times q} = \langle e_1, \dots, e_q \rangle$.
- **Relations:** The p rows of A .
- The matrix diff. operator A is now the **matrix of relations** of M .

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Linear systems as **modules**

Q: How to describe the space of solutions in this language?

Theorem (B. MALGRANGE & E. NOETHER)

Let \mathcal{F} be the D -module where we seek the solutions.

$$\begin{array}{ccc} \mathrm{Hom}_D(M, \mathcal{F}) & \xrightarrow{\cong} & \mathrm{Sol}_{\mathcal{F}}(A) \\ \psi & \mapsto & \psi = (\psi(e_i)) \in \mathcal{F}^{q \times 1} \end{array}$$

is an isomorphism of ABELIAN groups.

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Linear systems vs. **modules**

Q: But where is the advantage?

A:

- $\text{Hom}_D(M, \mathcal{F})$ only depends on the *isomorphism type* of M .
- The D -module \mathcal{F} can be altered.

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The module M

Interpret the differential operator A as a map

$$A : D^{1 \times p} \rightarrow D^{1 \times q}.$$

Recover the D -module M as the **cokernel** of A

$$M := D^{1 \times q} / D^{1 \times p} A = \operatorname{coker}(F_1 \xrightarrow{A} F_0),$$

where $F_1 := D^{1 \times p}$ and $F_0 := D^{1 \times q}$.

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Linear systems vs. **modules**

In analysis we learn that the higher order scalar ODE (in u)

$$u_{xxx} + a(x)u_{xx} + b(x)u_x + c(x)u = 0$$

and the first order system (in u, v, w)

$$u_x = v, \quad v_x = w, \quad w_x + a(x)w + b(x)v + c(x)u = 0$$

are “equivalent”.

So consider the differential algebra $D = K(x)[\partial]$ and the corresponding differential operators

$$M_{\text{scl}} := \left(\partial^3 + a(x)\partial^2 + b(x)\partial + c(x) \right) \in D^{1 \times 1}$$

and

$$M_{\text{sys}} := \begin{pmatrix} \partial & -1 & 0 \\ 0 & \partial & -1 \\ c(x) & b(x) & \partial + a(x) \end{pmatrix} \in D^{3 \times 3}.$$

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$$M_{\text{scl}} := \text{coker}(D^{1 \times 1} \xrightarrow{M_{\text{scl}}} D^{1 \times 1}) \text{ and}$$

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The modules M_{scl} and M_{sys} are indeed isomorphic:

$$\alpha : M_{\text{scl}} \xrightarrow{\begin{pmatrix} 1 & 0 & 0 \end{pmatrix}} M_{\text{sys}}, \quad \beta : M_{\text{sys}} \xrightarrow{\begin{pmatrix} 1 \\ \partial \\ \partial^2 \end{pmatrix}} M_{\text{scl}}.$$

We call $M_{\text{scl}} \cong M_{\text{sys}}$ the module of **universal solutions**.

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Triangular systems and cascade integration

Any **filtration** of M , i.e., a chain of submodules

$$0 \leq L \leq M$$

leads to a **triangular** presentation matrix

$$M = \left(\begin{array}{c|c} N & \eta \\ \hline 0 & L \end{array} \right)$$

with $L = \text{coker}(L)$ and $N = M/L \cong \text{coker}(N)$.

Solving a triangular system \rightsquigarrow **cascade integration**.

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Overview

1 From linear systems to D -modules

- Differential consequences
- From systems to modules
- Advantages

2 Purity filtration

- Derived Categories
- The CARTAN-EILENBERG resolution
- Example

The evaluation map revisited

Recall, the evaluation map

$$\varepsilon : \begin{cases} M & \rightarrow & M^{**} \\ m & \mapsto & m \mapsto (\varphi \mapsto \varphi(m)) \end{cases} .$$

It is in general neither surjective nor injective. Its kernel

$$t_{-1}(M) = t(M) := \ker \varepsilon \quad (\text{torsion submodule})$$

yields the 2-step filtration

$$0 \leq t(M) \leq M.$$

$M/t(M)$	\longleftrightarrow	the under determined part of the system
$t(M)$	\longleftrightarrow	the over determined part of the system

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Purity filtration

Purity filtration

In fact, there is a finer filtration

$$\cdots \leq t_{-(c+1)}(M) \leq t_{-c}(M) \leq \cdots \leq t_{-1}(M) \leq t_0(M) := M$$

called the **purity filtration**. The graded part

$$M_c := t_{-c}(M) / t_{-(c+1)}(M)$$

is called **pure** of grade c .

Is there a way to recover the complete purity filtration?

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Is there a way to recover the complete purity filtration?

Functors prefer complexes with adapted objects

Part 1 of the answer: The derived category formalism

The target of the evaluation map $\varepsilon : M \rightarrow M^{**}$ involves applying two functors to the module M :

$$M^{**} := F(G(M)), \text{ with}$$

$$F := \text{Hom}_D(-, D_D), G := \text{Hom}_D(-, {}_D D)$$

- Since VERDIER'S thesis we know that it is better to apply functors to complexes with **adapted** objects rather than to modules.

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A free resolution

Let $D = R[\partial_x, \partial_y, \partial_z]$ and $M = D/\langle \partial_x, \partial_y, \partial_z \rangle$ with resolution P_\bullet :

$$\begin{array}{ccccccccc}
 0 & \longleftarrow & D^{1 \times 1} & \xleftarrow{\text{grad}} & D^{1 \times 3} & \xleftarrow{\text{rot}} & D^{1 \times 3} & \xleftarrow{\text{div}} & D^{1 \times 1} & \longleftarrow & 0 \\
 \downarrow & & \downarrow & & \downarrow & & \downarrow & & \downarrow & & \downarrow \\
 0 & \longleftarrow & M & \longleftarrow & 0 & \longleftarrow & 0 & \longleftarrow & 0 & \longleftarrow & 0
 \end{array}$$

$\text{grad} \begin{pmatrix} \partial_x \\ \partial_y \\ \partial_z \end{pmatrix}$
 $\text{rot} \begin{pmatrix} 0 & \partial_z & -\partial_y \\ -\partial_z & 0 & \partial_x \\ \partial_y & -\partial_x & 0 \end{pmatrix}$
 $\text{div} \begin{pmatrix} \partial_x & \partial_y & \partial_z \end{pmatrix}$

- P_\bullet : adapted objects but complicated morphisms
- M : complicated object

The module vs. its resolution

Let us demonstrate VERDIER's statement on the dualizing functors $G := \text{Hom}_D(-, {}_D D)$ and $F := \text{Hom}_D(-, D_D)$:

$$M = D / \langle \partial_x, \partial_y, \partial_z \rangle \neq 0$$

$$P_\bullet : \quad 0 \longleftarrow D^{1 \times 1} \xleftarrow{\begin{pmatrix} \partial_x \\ \partial_y \\ \partial_z \end{pmatrix}} D^{1 \times 3} \longleftarrow D^{1 \times 3} \longleftarrow D^{1 \times 1} \longleftarrow 0$$

$$M^{**} = 0 \quad \text{while} \quad P^{**} \cong P.$$

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$$M^* = \text{Hom}(M, D) = 0$$

$$P_{\bullet}^* : \quad 0 \longrightarrow D^{1 \times 1} \xrightarrow{\begin{pmatrix} \partial_x \\ \partial_y \\ \partial_z \end{pmatrix}} D^{3 \times 1} \longrightarrow D^{3 \times 1} \longrightarrow D^{1 \times 1} \longrightarrow 0$$

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Quasi-isomorphisms

- Any projective resolution $P_\bullet : 0 \leftarrow P_0 \leftarrow P_1 \leftarrow P_2 \leftarrow \dots$ of a module M is such a complex with adapted objects.
- The natural epimorphism $M \xleftarrow{\nu} P_0$ induces a quasi-isomorphism of complexes, where M is now regarded as a complex concentrated in degree 0:

$$\begin{array}{ccc}
 P_\bullet & : & 0 \longleftarrow P_0 \longleftarrow P_1 \longleftarrow P_2 \longleftarrow \dots \\
 \nu \downarrow \cong & & \downarrow \quad \downarrow \quad \downarrow \quad \downarrow \\
 M & : & 0 \longleftarrow M \longleftarrow 0 \longleftarrow 0 \longleftarrow \dots
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Functors prefer complexes with adapted objects

Recall, we are interested in a substitute for the evaluation map

$$\varepsilon : M \rightarrow M^{**} = F(G(M))$$

which yields the complete purity filtration.

Answer:

- Instead of the module $G(M)$ consider the complex $G(P_\bullet)$.
- Instead of applying F to the complex $G(P_\bullet)$ apply it to a resolution T^\bullet of $G(P_\bullet)$.
- Fortunately there is a resolution T^\bullet of $G(P_\bullet)$ which is a **bifiltered** complex.
- It is the **total complex** of the so-called **CARTAN-EILENBERG bicomplex**.

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The CARTAN-EILENBERG resolution

$$G(P_{\bullet}) : \quad G(P_0) \longrightarrow G(P_1) \longrightarrow G(P_2) \longrightarrow \cdots$$

The CARTAN-EILENBERG resolution

$$\begin{array}{ccccccc} G(P_\bullet) : & & G(P_0) & \longrightarrow & G(P_1) & \longrightarrow & G(P_2) & \longrightarrow & \cdots \\ & & \uparrow & & \uparrow & & \uparrow & & \\ B^{\bullet,0} : & & B^{0,0} & \longrightarrow & B^{1,0} & \longrightarrow & B^{2,0} & \longrightarrow & \cdots \end{array}$$

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$$T^\bullet := \text{Tot}(B^{\bullet\bullet}) :$$

The CARTAN-EILENBERG resolution

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- The total complex T^\bullet of the CARTAN-EILENBERG bicomplex $B^{\bullet\bullet}$ is **bifiltered** in a natural way.

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The CARTAN-EILENBERG resolution

Induced filtrations

- M is the only homology of the bifiltered complex $F(T^\bullet)$. In other words there is a quasi-isomorphism

$$\varepsilon_\bullet : M \longrightarrow F(T^\bullet).$$

In particular, M is a subfactor of the bifiltered module $F(T^0)$.

- Any filtration of an object in an ABELIAN category induced a filtration on any of its subfactor objects.
- Hence, any filtration on a complex induces a filtration on its (co)homology objects.

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The purity filtration

Solution

The isomorphism

$$\varepsilon_{\bullet} : M \longrightarrow F(T^{\bullet})$$

provides the solution:

The first filtration on $F(T^{\bullet})$ induces the trivial filtration on its homology M , while the second filtration induces the **purity filtration** on M .

This filtration can be computed directly or in terms of spectral sequences:

$$E_{pq}^2 = \text{Ext}^{-p}(\text{Ext}^q(M, D), D) \implies M \text{ for } p + q = 0.$$

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Computability

All the above can be made computable in any ABELian category, in which all existential quantifiers appearing in the axioms can be turned into constructive ones [Bar]. The `homalg` project [hpa11] provides an implementation in this generality.

Definitions

- We call such an ABELian category computable.
- We call a ring D computable, if one can algorithmically solve (in)homogeneous linear systems over D .

[BLH11, Theorem 3.4]

The category of finitely presented modules over a computable ring D is ABELian and as such computable.

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An example over the WEYL algebra

Example: A module M over $D = k[x, y, z][\partial_x, \partial_y, \partial_z]$

The purity filtration of the module

$$M := \text{coker} \begin{pmatrix} \partial_y \partial_z - \frac{1}{3} \partial_z^2 + \frac{1}{3} \partial_x + \partial_y - \frac{1}{3} \partial_z & \partial_y \partial_z - \frac{1}{3} \partial_z^2 \\ \partial_x \partial_z + \partial_z^2 + \partial_z & \partial_x \partial_z + \partial_z^2 \\ \partial_z^2 - \partial_x + \partial_z & 3 \partial_x \partial_y + \partial_z^2 \\ \partial_x \partial_y & 0 \\ \partial_z^2 - \partial_x + \partial_z & -3 \partial_x^2 + \partial_z^2 \\ \partial_x^2 & 0 \\ x \partial_z^2 - x \partial_x + \frac{3}{2} \partial_x + x \partial_z + \frac{3}{2} \partial_z + \frac{3}{2} & x \partial_z^2 + \frac{3}{2} \partial_x + \frac{3}{2} \partial_z \\ \partial_z^3 + 2 \partial_z^2 + \partial_z & \partial_z^3 + \partial_x \partial_z + \partial_z^2 \end{pmatrix}$$

An example over the WEYL algebra

Example: A module M over $D = k[x, y, z][\partial_x, \partial_y, \partial_z]$

is given by an isomorphism onto

$$H_0(\text{Tot}_\bullet B_{\bullet\bullet}) = \text{coker} \begin{pmatrix} \boxed{\partial_x} & 1 & \cdot \\ \cdot & \boxed{\partial_x} & 1 \\ \cdot & \boxed{\partial_y} & 1 \\ \cdot & \cdot & \boxed{\partial_x} \\ \cdot & \cdot & \boxed{\partial_y} \\ \cdot & \cdot & \boxed{\partial_z} \end{pmatrix}.$$

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has the general solution:

$$u(x, y, z) = C_1(y, z) + (x + y)C_2(z) + \bar{C}_2(z) + \frac{x^2 + 2xy + y^2}{2}C_3.$$

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Leading to the isomorphism

$$M \xrightarrow{L} C = \operatorname{coker} \begin{pmatrix} \partial_x^2 - \partial_x \partial_y \\ \partial_x \partial_y^2 \\ \partial_x \partial_y \partial_z \end{pmatrix}$$

with

$$L = \begin{pmatrix} 2x\partial_x\partial_y - \partial_x - \partial_z \\ -2x\partial_x\partial_y + \partial_x + \partial_z + 1 \end{pmatrix}.$$

The desired general solution of the original system is then Lu .

An example over the WEYL algebra

Example: A module M over $D = k[x, y, z][\partial_x, \partial_y, \partial_z]$

Leading to the isomorphism

$$M \xrightarrow{L} C = \operatorname{coker} \begin{pmatrix} \partial_x^2 - \partial_x \partial_y \\ \partial_x \partial_y^2 \\ \partial_x \partial_y \partial_z \end{pmatrix}$$

with

$$L = \begin{pmatrix} 2x\partial_x\partial_y - \partial_x - \partial_z \\ -2x\partial_x\partial_y + \partial_x + \partial_z + 1 \end{pmatrix}.$$

The desired general solution of the original system is then Lu .

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ABELian algorithms

- Computers appreciate abstractness
 - Code simplicity
 - Maintenance
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Using the same abstract implementation we want to compute the **BEILINSON spectral sequence** of the bicomplex

$$B^e = \bigoplus_j H^j(\mathcal{F}(e - j)) \otimes \Omega_{\mathbb{P}^n}^{j-e}(j - e)$$

and the induced filtration on the sheaf $\mathcal{F} \in \mathcal{Coh}(\mathbb{P}^n)$.

Thank you for your attention

-  Mohamed Barakat, *Spectral filtrations via generalized morphisms*, submitted (arXiv:0904.0240).
-  Mohamed Barakat and Markus Lange-Hegermann, *An axiomatic setup for algorithmic homological algebra and an alternative approach to localization*, J. Algebra Appl. **10** (2011), no. 2, 269–293, (arXiv:1003.1943).
-  The homalg project authors, *The homalg project*, 2003-2011, (<http://homalg.math.rwth-aachen.de/>).