Dynamic Topological Logic Day 2

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$$\llbracket \Box \varphi \rrbracket = \bigcap_{n < \omega} S^{-n} \llbracket \varphi \rrbracket$$
 (henceforth).

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- The full logic over the class of dynamical systems with a homeomorphism is non-axiomatizable.
- The full logic over the class of all dynamical systems is undecidable.
- The formula □■p → ■□p is Kripke-valid, but not topologically valid.
- A formula is satisfiable iff it is satisfiable on a non-deterministic quasimodel.



1. Extend the language of DTL to obtain a natural axiomatization





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2. Exhibit a decidable sub-language which remains expressive enough to reason about asymptotic behaviour

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Fix a consistent formula φ . We construct a model for φ .

1. Assign a characteristic formula to each possible moment \mathfrak{m} .

In this case, \mathfrak{m} is a Σ -type and $\chi(\mathfrak{m}) = \bigwedge \mathfrak{m}^+ \land \neg \bigvee \mathfrak{m}^-$.

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4. Conclude that any possible moment can be included in a realizing path an hence an LTL model.

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- 3. The moment \mathfrak{m} is possible iff $Sim(\mathfrak{m})$ is consistent. Define \mathcal{J}_{Σ} to be the set of possible moments.
- 4. Prove that \mathcal{J}_{Σ} is a quasimodel.
- 5. Conclude that if φ is consistent then it is true on some possible moment, hence on the quasimodel \mathcal{J}_{Σ} , and hence on some dynamic topological model (by last week's results).

Fix a finite set of formulas Σ closed under subformulas.

Recall: A Σ -type is a pair (Φ^+ , Φ^-) indicating the true and false formulas of Σ on a point.

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Note: Labelled spaces generalize topological models since we may always define

$$\ell^+(\mathbf{x}) = \{\varphi \in \Sigma : \mathbf{x} \in \llbracket \varphi \rrbracket\} \\ \ell^-(\mathbf{x}) = \{\varphi \in \Sigma : \mathbf{x} \notin \llbracket \varphi \rrbracket\}$$

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Simulations revisited

A simulation between labelled spaces (X, ℓ_X) and (Y, ℓ_Y) is a continuous relation $E \subset X \times Y$ which preserves labels:

$$x E y \Rightarrow \ell_X(x) = \ell_Y(y)$$

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Simulations between labelled preorders are forward-confluent:



Reminder: The structure \mathcal{I}_{Σ}

$$\mathcal{I}_{\Sigma} = \left(\textit{I}_{\Sigma}, \succcurlyeq, \textit{R}, \ell\right)$$

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- v R w if there is a sensible, root-preserving relation between v and w

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Today: The relation \trianglelefteq defines a well quasiorder on \mathcal{I}_{Σ} .

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2. If $U \subset A$ is upwards-closed under \leq , there are finitely many

 $u_1,\ldots,u_n\in A$

such that for every $a \in A$ there is $i \leq n$ with $u_i \leq a$.

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Theorem (Kruskal)

Fix a finite set Λ . The set of finite trees labelled by elements of Λ is well quasiordered by embeddability.

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Proof.

Every moment \mathfrak{m} is bisimilar to a tree-like moment \mathfrak{m}' , and an embedding *E* from \mathfrak{m}' to \mathfrak{n}' yields a simulation between \mathfrak{m} and \mathfrak{n} . So, we can apply Kruskal's tree theorem.

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First used in the setting of DTL in Konev, Kontchakov, Wolter and Zakharyaschev 2006.

Undefinability of simulation

Proposition

The property $\mathfrak{m} \trianglelefteq (X, \ell, x)$ is not definable in $\mathcal{L}_{\blacksquare}$, even when X is a Kripke model and \mathfrak{m} is the {**p**, *q*}-cluster.

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The tangled closure

Definition

If S is a collection of subsets of a topological space X, we define the tangled closure of S, denoted S^* , as the greatest subset of X such that every $A \in S$ is dense within S^* .

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 $\mathcal{L}^*_{\blacksquare(\circ\Box)}$: We consider an extension of L where \blacklozenge is allowed to act on *sets* of formulas, and define

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Theorem (Dawar and Otto)

 $\mathcal{L}^*_{\blacksquare}$ is equally expressive as the μ -calculus over the class of finite preorders.

The tangled closure on a preorder

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If W is finite then w ∈ [[◆{φ₀,...,φ_n}]] iff there is a cluster C ≽ w such that for each i ≤ n there is v ∈ C such that v ∈ [[φ_i]].

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- If W is finite then w ∈ [[◆{φ₀,...,φ_n}]] iff there is a cluster C ≽ w such that for each i ≤ n there is v ∈ C such that v ∈ [[φ_i]].
- ▶ In general, $w \in [[\blacklozenge \{\varphi_0, ..., \varphi_n \}]]$ iff there is a path

$$W = W_0 \preccurlyeq W_1 \preccurlyeq W_2 \preccurlyeq \dots$$

such that for each $i \leq n$ there are infinitely many j such that $w_j \in [\![\varphi_i]\!]$.

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4. If $A = \mathbb{Q}$ and $B = \mathbb{Q} + \pi$ then $\{A, B\}^*$

1. If
$$A = (-\infty, 0)$$
 and $B = (0, \infty)$ then $\{A, B\}^* = \emptyset$

2. If
$$A = (-\infty, 0)$$
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4. If $A = \mathbb{Q}$ and $B = \mathbb{Q} + \pi$ then $\{A, B\}^* = \mathbb{R}$

Theorem (DFD)

Given a locally finite labelled preorder (W, \preccurlyeq, ℓ) , there exist formulas $(Sim(w))_{w \in W} \in \mathcal{L}^*_{\blacksquare}$ such that for any dynamic topological model $\mathcal{M} = (X, S, \llbracket \cdot \rrbracket)$, tfae:

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Example If \mathfrak{m} is the {**p**, q}-cluster then

$$\mathit{Sim}(\mathfrak{m}) = p \land \blacklozenge \{p,q\}$$

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Taut

All propositional tautologies.

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Taut Axioms for ■:

All propositional tautologies.

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$$\begin{array}{ll} \mathsf{K} & \blacksquare(p \to q) \to (\blacksquare p \to \blacksquare q) \\ \mathsf{T} & \blacksquare p \to p \\ \mathsf{4} & \blacksquare p \to \blacksquare \blacksquare p \\ \mathsf{Fix}_{\blacklozenge} & \blacklozenge \Gamma \to \bigwedge_{\gamma \in \Gamma} \blacklozenge(\gamma \land \blacklozenge \Gamma) \\ \mathsf{Ind}_{\blacklozenge} & p \land \blacksquare \Bigl(p \to \bigwedge_{\gamma \in \Gamma} \blacklozenge(p \land \gamma) \Bigr) \to \blacklozenge \Gamma \end{array}$$

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Temporal axioms:

Neg $\neg \circ p \leftrightarrow \circ \neg p$ And $\circ (p \land q) \leftrightarrow \circ p \land \circ q$ $\mathsf{Fix}_{\Box} \quad \Box p \to p \land \circ \Box p$ Ind_{\Box} $\Box(p \rightarrow \circ p) \rightarrow (p \rightarrow \Box p)$

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TCont

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Rules:

The set of possible moments

Definition

Fix finite Σ closed under subformulas. A moment \mathfrak{m} of \mathcal{I}_{Σ} is possible if $Sim(\mathfrak{m})$ is consistent, and \mathcal{J}_{Σ} is the substructure of possible moments.

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Completeness proof strategy:

1. Prove that \mathcal{J}_{Σ} is a quasimodel.

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Completeness proof strategy:

1. Prove that \mathcal{J}_{Σ} is a quasimodel.

 Prove that for any consistent φ, there is a possible moment m with φ ∈ ℓ⁺(m).

Fix finite Σ closed under subformulas and let $\mathcal{I}_{\Sigma} = (I_{\Sigma}, \succcurlyeq, R, \ell)$

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$$\blacktriangleright \vdash Sim(w) \rightarrow \circ \bigvee_{wRv} Sim(v)$$

Lemma

Let w be a moment of \mathcal{J}_{Σ} and $\Box \psi \in \ell^{-}(w)$, $R^{*}(w)$ be the set of worlds reachable from w in \mathcal{J}_{Σ} Then, $\psi \in \ell^{-}(v)$ for some $v \in R^{*}(w)$

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$$\vdash Sim(w) \rightarrow \Box \psi$$

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Theorem (DFD) If $\varphi \in \mathcal{L}^*_{\blacksquare \circ \Box}$ is valid on the class of dynamical posets then $\vdash \varphi$

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Proof. Assume that φ is consistent.

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we obtain that w_* is possible for some w_* with $\varphi \in \ell^+(w_*)$, hence w_* is a world of \mathcal{J}_{Σ} .

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we obtain that w_* is possible for some w_* with $\varphi \in \ell^+(w_*)$, hence w_* is a world of \mathcal{J}_{Σ} .

Thus \mathcal{J}_{Σ} is a quasimodel satisfying φ , and it follows that φ is satisfiable on some dynamical topological model.

Kremer's intuitionistic temporal logic

Kremer 2004: Work over $\mathcal{L}_{\circ\square}$ and use the topological semantics of intuitionistic logic to interpret \rightarrow

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However, the following standard validities fail







Topological semantics for intuitionistic logic

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Models

- $\mathcal{M} = (X, \mathcal{T}, V)$, where:
 - (X, \mathcal{T}) is a topological space
 - $\blacktriangleright V : \mathbb{PV} \to \mathcal{T}$

Topological semantics for intuitionistic logic

Models

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 - $\blacktriangleright V : \mathbb{PV} \to \mathcal{T}$

Truth sets

- $\blacktriangleright \ \llbracket \bot \rrbracket = \varnothing$
- $\blacktriangleright \llbracket p \rrbracket = V(p)$
- $\blacktriangleright \ \llbracket \varphi \land \psi \rrbracket = \llbracket \varphi \rrbracket \cap \llbracket \psi \rrbracket$

- $\blacktriangleright \ \llbracket \varphi \lor \psi \rrbracket = \llbracket \varphi \rrbracket \cup \llbracket \psi \rrbracket$
- $\blacktriangleright \ \llbracket \varphi \to \psi \rrbracket$
 - $= \left(\llbracket \varphi \rrbracket^{c} \cup \llbracket \psi \rrbracket \right)^{\circ}$

Interior of $A \subseteq X$:

$$A^\circ = \bigcup \{ U \in \mathcal{T} : U \subseteq A \}$$

Classical regions



$\llbracket p \rrbracket$

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Classical regions



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Classical regions



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Intuitionistic regions





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 $\llbracket p \rrbracket$











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 $\llbracket p \lor \neg p \rrbracket'$

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 $\llbracket p \lor \neg p \rrbracket'$ Fails!

Intuitionistic temporal logic

Language $\mathcal{L}_{\circ \Diamond \Box \forall}$: $\varphi, \psi :=$

$$\boldsymbol{\rho} \mid \perp \mid \varphi \land \psi \mid \varphi \lor \psi \mid \varphi \rightarrow \psi \mid \circ \varphi \mid \Diamond \varphi \mid \Box \varphi \mid \forall \varphi$$

Models: (X, S, V), where $S: X \to X$ is continuous



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Truth of temporal operators

$$\begin{split} \llbracket \circ \varphi \rrbracket &= S^{-1} \llbracket \varphi \rrbracket & \qquad \llbracket \Box \varphi \rrbracket &= \left(\bigcap_{n < \omega} S^{-n} \llbracket \varphi \rrbracket \right)^{\circ} \\ \llbracket \diamond \varphi \rrbracket &= \bigcup_{n < \omega} S^{-n} \llbracket \varphi \rrbracket & \qquad \llbracket \forall \varphi \rrbracket = \begin{cases} X & \text{if } \llbracket \varphi \rrbracket = X \\ \varnothing & \text{otherwise} \end{cases} \end{split}$$

Gödel-Tarski translation

The translation $\varphi \mapsto \varphi^{\blacksquare}$ embeds $\mathcal{L}_{\circ \Diamond \Box}$ into the classical $\mathcal{L}_{\blacksquare \circ \Box}$ by setting

$$p^{\bullet} = \blacksquare p \qquad \qquad \flat \quad \bot^{\bullet} = \bot$$

$$(\varphi \land \psi)^{\bullet} = \varphi^{\bullet} \land \psi^{\bullet} \qquad \qquad \flat \quad (\varphi \lor \psi)^{\bullet} = \varphi^{\bullet} \lor \psi^{\bullet}$$

$$(\varphi \rightarrow \psi)^{\bullet} = \blacksquare (\varphi^{\bullet} \rightarrow \psi^{\bullet}) \qquad \flat \quad (\circ \varphi)^{\bullet} = \circ \varphi^{\bullet}$$

$$(\Diamond \varphi)^{\bullet} = \Diamond \varphi^{\bullet} \qquad \qquad \flat \quad (\Box \varphi)^{\bullet} = \blacksquare \Box \varphi^{\bullet}$$

Theorem

Given $\varphi \in \mathcal{L}_{\circ \Diamond \Box}$, φ is intuitionistically valid iff φ^{\blacksquare} is classically valid.

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Corollary

The set of $\mathcal{L}_{\circ \Diamond \Box}$ -formulas valid over the class of dynamical systems is computably enumerable.

Kremer's counterexample: $\Box p \rightarrow \circ \Box p$ fails!





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Recall: A dynamical system (X, S) is Poincaré recurrent if whenever A ⊆ X is open and non-empty, there are x ∈ A and n > 0 such that Sⁿ(x) ∈ A.

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Recall: This is equivalent to the classical validity of

 $\blacksquare \varphi \to \blacklozenge \circ \diamondsuit \varphi$



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It is also equivalent to the intuitionistic validity of

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▶ **Recall:** (*X*, *S*) is minimal if for all $x \in X$ and non-empty, open $A \subseteq X$ there is n > 0 such that $S^n(x) \in A$.

Recall: A dynamical system (X, S) is Poincaré recurrent if whenever A ⊆ X is open and non-empty, there are x ∈ A and n > 0 such that Sⁿ(x) ∈ A.
 Recall: This is equivalent to the classical validity of

 φ → ♦○◊φ

It is also equivalent to the intuitionistic validity of

 $p \rightarrow \neg \neg \circ \Diamond p$

Recall: (X, S) is minimal if for all x ∈ X and non-empty, open A ⊆ X there is n > 0 such that Sⁿ(x) ∈ A.
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Recall: A dynamical system (X, S) is Poincaré recurrent if whenever A ⊆ X is open and non-empty, there are x ∈ A and n > 0 such that Sⁿ(x) ∈ A.
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Some good news

Theorem (DFD)

The validity problem for $\mathcal{L}_{\circ \Diamond \forall}$ is decidable over the class of all dynamical systems

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However, there are Kripke-valid but non-derivable formulas, such as

 $\Box(p \lor q) \to \Diamond p \lor \Box q$

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Triple (W, \preccurlyeq, ℓ) where ℓ assigns a type to each $w \in W$ according to the intuitionistic semantics

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In the intuitionitsic setting, we may use a finite version of \mathcal{I}_{Σ} .

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There are finitely many (about 2^n_n) moments of height *n* up to bisimulation.

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The calculus ITL^0_{\Diamond}

ITaut Standard intuitionistic propositional axioms Temporal axioms:

$Next_{\perp}$	$\neg \circ \bot$		
$Next_{\wedge}$	$(\circ \varphi \wedge \circ \psi) ightarrow \circ (\varphi \wedge \psi)$		
Next_{\vee}	$\circ(\varphi \lor \psi) \to (\circ \varphi \lor \circ \psi)$		
$\text{Next}_{\rightarrow}$	$\circ(\varphi ightarrow \psi) ightarrow (\circ \varphi ightarrow \circ \psi)$		
Fix_{\Diamond}	$(\varphi \vee \circ \Diamond \varphi) \to \Diamond \varphi$		
Rules:			
MP	$\frac{\varphi \ \varphi \to \psi}{\psi}$	Nec	$\frac{\varphi}{\circ \varphi}$
Mon	$\frac{\varphi \to \psi}{1 \to 1}$	Ind	$\frac{\circ\varphi\to\varphi}{\bullet}$

 $\Diamond \varphi \to \Diamond \psi$

 $\Diamond \varphi \to \varphi$

Add the following to ITL^0_{\Diamond} :

K_\forall	$\forall (\varphi \to \psi) \to (\forall \varphi \to \forall \psi)$	EM_\forall	$\forall \varphi \vee \neg \forall \varphi$
Dist∀	$\forall (\varphi \lor \forall \psi) \to \forall \varphi \lor \forall \psi$	T_\forall	$\forall \varphi \to \varphi$
Next∀	$\forall \varphi \leftrightarrow \circ \forall \varphi$	$4_{orall}$	$\forall \varphi \rightarrow \forall \forall \varphi$
Nec∀	$\frac{\varphi}{\forall \varphi}$		

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Theorem (Boudou, Diéguez, DFD)

 ITL^0_{\Diamond} and $ITL^0_{\Diamond\forall}$ are sound and complete for the class of dynamical systems.

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Question: Are these logics also Kripke complete?

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Falsifying $\forall (\neg p \lor \Diamond p) \to (\Diamond p \lor \neg \Diamond p)$ topologically





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 $(\neg p \lor \Diamond p)$

$$\forall (\neg p \lor \Diamond p) \neg \Diamond p$$

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$$\overset{\Diamond p}{\underset{(\neg p \lor \Diamond p)}{}^{\bigcirc}} \overset{\bigcirc}{\neg \Diamond p}$$

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Simulation formulas

Theorem

Given a finite labelled poset A with domain W, there exist intuitionistic formulas $(Sim(w))_{w \in W}$ such that for any model $\mathcal{M} = (X, \preccurlyeq, V)$, tfae:

- 1. $(\mathcal{M}, x) \not\models Sim(w)$
- 2. there is $y \succcurlyeq x$ and a simulation $E \subseteq W \times X$ such that $w \in y$

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(Essentially Jankov-de Jongh formulas)

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(Essentially Jankov-de Jongh formulas)

Definition

Fix finite Σ closed under subformulas. A world *w* of \mathcal{I}_{Σ} is possible if $\not\vdash Sim(w)$, and \mathcal{J}_{Σ} is the substructure of possible worlds

Completeness of $ITL_{\Diamond\forall}^0$

Proof. ITL $^0_{\Diamond\forall}$ is complete for the class of dynamical systems.

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Completeness of $ITL_{\Diamond\forall}^0$

Proof.

 $ITL_{\Diamond\forall}^{0}$ is complete for the class of dynamical systems.

1. Unlike in the classical case, simulation formulas *Sim(w)* are already definable in the basic intuitionistic language (no **tangle** needed).

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Completeness of $ITL_{\Diamond\forall}^0$

Proof.

 $ITL_{\Diamond\forall}^{0}$ is complete for the class of dynamical systems.

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Completeness of ITL⁰

Proof.

 $ITL_{\Diamond\forall}^{0}$ is complete for the class of dynamical systems.

- 1. Unlike in the classical case, simulation formulas *Sim*(*w*) are already definable in the basic intuitionistic language (no **tangle** needed).
- 2. With these formulas, the classical completeness proof goes through.
- We only need to make slight modifications to work with the dual ◊.

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 - 1. Identification of tractable fragments
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Concluding remarks

- Dynamic topological logic is an expressive propositional framework in which to reason about topological dynamics
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Concluding remarks

- Dynamic topological logic is an expressive propositional framework in which to reason about topological dynamics
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 - 4. ...

Thank you for your attention!

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