Dynamic Topological Logic Day 1

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Dynamical systems are abstract models of change over time and occur in many branches of mathematics and natural science.

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Formally, a dynamical (topological) system is a pair (X, S) where X is a topological space and $S: X \to X$ is continuous.

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A point $x \in X$ 'moves' along its orbit

$$x, S(x), S^2(x), \ldots, S^n(x), \ldots$$

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Recall:

A topological space is a pair (X, \mathcal{T}) where $\mathcal{T} \subseteq 2^X$ satisfies

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Example

The real line \mathbb{R} is equipped with its standard topology where $U \subseteq \mathbb{R}$ is open iff

$$\forall x \in U \exists \varepsilon > 0 \forall y \in \mathbb{R} (|x - y| < \varepsilon \Rightarrow y \in U)$$

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More Examples of Topological Spaces

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For any n, \mathbb{R}^n has a standard topology generated by open balls

$$B_{\varepsilon}(x) = \{y \in \mathbb{R}^n : d(x,y) < \varepsilon\}$$

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If (W, ≼) is a partially ordered set, then W can be endowed with the down-set topology by letting U ⊂ W be open if

$$\forall w \succcurlyeq v \ (w \in U \Rightarrow v \in U).$$

The up-set topology is defined dually.

 $S \colon \mathbb{R} o \mathbb{R}$ is continuous if

 $\forall x \in \mathbb{R} \forall \varepsilon > 0 \exists \delta > 0 \ (d(x, y) < \delta \Rightarrow d(S(x), S(y)) < \varepsilon)$

 $\mathcal{S} \colon \mathbb{R} \to \mathbb{R}$ is continuous if

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More generally, $S: X \to Y$ is continuous if $U \subset Y$ is open $\Rightarrow S^{-1}(U)$ is open.

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More generally, $S: X \to Y$ is continuous if $U \subset Y$ is open $\Rightarrow S^{-1}(U)$ is open.

If moreover S(U) is open whenever U is open we say S is an interior map.

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Examples

- $S \colon \mathbb{R} \to \mathbb{R}$ is continuous whenever *S* is a polynomial.
- If (W, ≼) is a preorder then S: W → W is continuous iff increasing:

$$\forall \mathbf{v}, \mathbf{w} \ \big(\mathbf{w} \preccurlyeq \mathbf{v} \Rightarrow \mathbf{S}(\mathbf{w}) \preccurlyeq \mathbf{S}(\mathbf{v}) \big)$$

A dynamical system (X, S) is probability preserving if for all open A ⊂ X, |A| = |S⁻¹(A)|, where |A| denotes probability (or volume).

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- A dynamical system (X, S) is Poincaré recurrent (for our purposes) if whenever A is non-empty and open there are x ∈ A and n > 0 such that Sⁿ(x) ∈ A.

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Theorem (Poincaré)

Every probability-preserving system is Poincaré recurrent.

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Theorem (Poincaré)

Every probability-preserving system is Poincaré recurrent.

A dynamical system (X, S) is minimal if whenever A is non-empty and open and x ∈ X, there is n > 0 such that Sⁿ(x) ∈ A.

A Minimal System



A Probability-Preserving System



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Language $(\mathcal{L}_{\blacksquare\circ})$:

$\boldsymbol{\rho} \mid \neg \varphi \mid \varphi \land \psi \mid \blacksquare \varphi \mid \circ \varphi$

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Models: $(X, S, \llbracket \cdot \rrbracket)$ consisting of a dynamical system equipped with a valuation $\llbracket \cdot \rrbracket : \mathcal{L}_{\blacksquare \circ} \to 2^X$ such that

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$$\blacktriangleright \ \llbracket \blacksquare \varphi \rrbracket = \llbracket \varphi \rrbracket^{\circ} \text{ (interior)}$$

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Introduced by Artemov, Davoren and Nerode (1997).

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Taut Axioms for ■:

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$$egin{aligned} & \blacksquare(p o q) o (\blacksquare p o \blacksquare q) \ & \blacksquare p o p \ & \blacksquare p o \blacksquare \blacksquare p \end{aligned}$$



Temporal axioms:

$$\begin{array}{ll} \mathsf{Neg}_{\circ} & \neg \circ p \leftrightarrow \circ \neg p \\ \mathsf{And}_{\circ} & \circ (p \land q) \leftrightarrow \circ p \land \circ q \end{array}$$

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Positive results on S4C

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Proof idea: The canonical model satisfies all frame conditions.

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Beware: Filtration does not preserve the monotonicity condition on *S*, so other techniques are needed.

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- 2006 DFD showed that S4C is complete for interpretations on \mathbb{R}^2 .

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Language ($\mathcal{L}_{\blacksquare \circ \Box}$): $p \mid \neg \varphi \mid \varphi \land \psi \mid \blacksquare \varphi \mid \circ \varphi \mid \Box \varphi$

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Semantics:

•
$$\llbracket \Box \varphi \rrbracket = \bigcap_{n < \omega} S^{-n} \llbracket \varphi \rrbracket$$
 (henceforth).

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Equivalently, x satisfies □φ if φ holds on every point of the orbit of x:

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• Its dual is $\diamond := \neg \Box \neg$ (eventually).

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Introduced by Kremer and Mints (2005).

Kremer and Mints axioms

Kremer and Mints proposed the axiomatization KM of DTL given by

$$\mathsf{KM} = \mathsf{S4C} + \mathsf{Fix}_{\Box} + \mathsf{Ind}_{\Box} + \mathsf{N}_{\Box}$$

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where

$$\begin{array}{ll} \mathsf{Fix}_{\Box} & \Box p \to p \land \circ \Box p \\ \mathsf{Ind}_{\Box} & \Box (p \to \circ p) \to (p \to \Box p) \end{array}$$

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This is the natural axiomatization obtained by combining S4C with Linear Temporal Logic (LTL).

Kremer and Mints left the question of completeness open.

Recall that a dynamical system (X, S) is Poincaré recurrent if whenever A ⊆ X is open and non-empty, there are x ∈ A and n > 0 such that Sⁿ(x) ∈ A.

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This is equivalent to the validity of

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This is equivalent to the validity of

 $\exists \blacksquare \varphi \to \forall \Diamond \varphi$

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Here, \forall and \exists are the universal modalities.

2005 Kremer and Mints showed that DTL cannot have the finite model property or even the locally finite model property.

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- 2006 Konev, Kontchakov, Wolter and Zakaryashev proved that
 - DTL is undecidable
 - DTL_H, where *f* is restricted to be a homeomorphism/interior map, is non-axiomatizable

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2014 DFD showed that DTL is not finitely axiomatizable, hence KM is incomplete.

The Post Correspondence Problem

Fix a sequence of pairs

$$P = ((\boldsymbol{v}_0, \boldsymbol{u}_0), \dots, (\boldsymbol{v}_k, \boldsymbol{u}_k))$$

with

$$oldsymbol{v}_i = oldsymbol{b}_0^i \dots oldsymbol{b}_{\ell_i}^i$$

 $oldsymbol{u}_i = oldsymbol{c}_0^i \dots oldsymbol{c}_{r_i}^i$

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words over some alphabet A.

Problem (PCP): Does there exist a sequence i_1, \ldots, i_N with

$$\boldsymbol{v}_{i_1}*\ldots*\boldsymbol{v}_{i_N}=\boldsymbol{u}_{i_1}*\ldots*\boldsymbol{u}_{i_N}?$$

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A Solvable PCP

$$\mathbf{v}_0 = ab$$
 $\mathbf{u}_0 = a$
 $\mathbf{v}_1 = d$ $\mathbf{u}_1 = cd$
 $\mathbf{v}_2 = c$ $\mathbf{u}_2 = b$

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 $\mathbf{v}_1 = d \quad \mathbf{u}_1 = cd$
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Then,

$$\boldsymbol{v}_0 \ast \boldsymbol{v}_2 \ast \boldsymbol{v}_1 = \boldsymbol{u}_0 \ast \boldsymbol{u}_2 \ast \boldsymbol{u}_1$$
$$= abcd$$

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Then,

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Theorem (Post)

The set of PCP instances without a solution is not computably enumerable.

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Goal: For an alphabet *A* and a PCP instance *P*, define $\varphi_{A,P}$ so that *P* has a solution iff $\varphi_{A,P}$ is satisfiable over the class of dynamical systems with an interior map.

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Some useful abbreviations:

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Some useful abbreviations:

$$(\textit{stripe} \rightarrow \blacklozenge(\neg \textit{stripe} \land \blacklozenge \varphi)) \land (\neg \textit{stripe} \rightarrow \blacklozenge(\textit{stripe} \land \blacklozenge \varphi))$$

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$$\blacktriangleright \ \textit{lw}_i = \textit{left}_{b_0^i} \land \blacklozenge_{\textit{stripe}} \left(\textit{left}_{b_2^i} \land \dots \land \blacklozenge_{\textit{stripe}} \textit{left}_{b_{\ell_i}^i}\right)$$

We will define

$$\varphi_{\mathsf{A},\mathsf{P}} := \varphi_{\mathsf{eq}} \land \varphi_{\mathsf{stripe}} \land \varphi_{\mathsf{left}} \land \varphi_{\mathsf{right}}$$

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The formula φ_{right} is defined similarly, replacing *left* by *right*, etc.

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The set of worlds W

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The relation \preccurlyeq

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The function S

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The valuation of end for \Diamond end

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The valuation of *stripe* for $\Box^{<end}$ \blacksquare (*stripe* $\leftrightarrow \circ$ *stripe*)



The coding of \boldsymbol{v}_0 and \boldsymbol{u}_0

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The coding of $\boldsymbol{v}_0 * \boldsymbol{v}_1$ and $\boldsymbol{u}_0 * \boldsymbol{u}_1$

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The coding of $\boldsymbol{v}_0 * \boldsymbol{v}_1 * \boldsymbol{v}_2$ and $\boldsymbol{u}_0 * \boldsymbol{u}_1 * \boldsymbol{u}_2$



The formula $\varphi_{eq} := \Diamond (end \land \bigwedge_{a \in A} \blacksquare (left_a \leftrightarrow right_a))$ is satisfied!

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Lemma

The following are equivalent:

1. The PCP instance (A, P) is solvable.

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Proof.

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Other implications require some care.

Beware: Topologically satisfiable formulas are not always Kripke-satisfiable.

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Non-axiomatizability and undecidability

Theorem

The set of $\mathcal{L}_{\blacksquare \circ \Box}$ formulas valid over the class of spaces with an interior map is not computably enumerable.

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The proof proceeds by a similar (but more involved) reduction of a reachability problem for lossy channel systems.

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Definition

A topological space X is Aleksandroff if arbitrary intersections of open sets are open.

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A space X is Aleksandroff iff the topology is the up-set topology generated by some partial order \preccurlyeq .

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 (\Leftarrow) Recall that the up-set topology consists of the sets that are upwards-closed under \preccurlyeq . It is not hard to check that such sets are closed under arbitrary intersections.

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 (\Rightarrow) If X is Alexandroff, define $x \preccurlyeq y$ if

$$y \in \bigcap \{ U : U \text{ is open and } x \in U \}$$

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Proposition The formula



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Kripke validity:

$$\llbracket \Box \blacksquare \rho \rrbracket \quad = \bigcap_{n=0}^{\infty} S^{-n} \llbracket \blacksquare \rho \rrbracket$$

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continuity $\subset \bigcap_{n=0}^{\infty} (S^{-n} \llbracket \rho \rrbracket)^{\circ}$

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$$X = \mathbb{R} \qquad \qquad \triangleright S(x) = 2x \\ \mathbb{p} = (-\infty, 1]$$



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In the sequel we discuss non-deterministic quasimodels and their applications to DTL.

A pair of sets of formulas $\Phi = (\Phi^+, \Phi^-)$ satisfying natural coherence conditions

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 $(\boldsymbol{p}\wedge\boldsymbol{q}$;)

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 $(\boldsymbol{p} \wedge \boldsymbol{q}, \boldsymbol{p}, \boldsymbol{q};)$

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 $(p \land q, p, q; \blacklozenge r)$



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Triple (W, \preccurlyeq, ℓ) where ℓ assigns a type to each $w \in W$ according to the Kripke semantics

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Tuple $(W, \preccurlyeq, S, \ell)$ consisting of a locally finite labelled preorder with a forward-confluent relation *S* satisfying semantic conditions of the successor relation

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A quasimodel falsifying $\Box \blacksquare p \rightarrow \blacksquare \Box p$



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From dynamical systems to quasimodels

Theorem

A formula $\varphi \in \mathcal{L}_{\blacksquare \circ \Box}$ is valid over the class of dynamical systems iff it is valid over the class of quasimodels

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 (\Rightarrow) Define a natural topology and transition function on the set of realizing paths

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 (\Leftarrow) Fix a finite set of formulas Σ closed under subformulas

- Construct an initial, weak quasimodel \mathcal{I}_{Σ}
- Prove that if φ ∈ Σ is topologically falsifiable, then it is falsifiable on some quasimodel Q ≤ I_Σ

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We define $\mathcal{I}_{\Sigma} = (\mathit{I}_{\Sigma}, \succcurlyeq, \mathit{R}, \ell)$ by

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Fact: \mathcal{I}_{Σ} is a weak quasimodel, but not necessarily a quasimodel.

Quasimodels by simulation

A simulation *E* between a weak quasimodel $Q = (W, \preccurlyeq, R, \ell)$ and a dynamic topological model $\mathcal{M} = (X, S, \llbracket \cdot \rrbracket)$ is a binary relation

$$E \subset W \times X$$

such that

- 1. *E* preserves types
- 2. *E* is continuous (preimages of opens are open)
- 3. *E* is dynamic if the following diagram can always be completed

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The maximal simulation

Let $Q = (W, \preccurlyeq, R, \ell)$ be a weak quasimodel, $\mathcal{M} = (X, S, \llbracket \cdot \rrbracket)$ a dynamic topological model.

Lemma

If $E \subseteq W \times X$ is a dynamic simulation, then the domain of E is a quasimodel.

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Proposition

Let $E^* \subseteq I_{\Sigma} \times X$ be the maximal simulation. Then, E^* is a surjective, dynamic simulation.

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If $E \subseteq W \times X$ is a dynamic simulation, then the domain of E is a quasimodel.

Proposition

Let $E^* \subseteq I_{\Sigma} \times X$ be the maximal simulation. Then, E^* is a surjective, dynamic simulation.

So, any topologically satisfiable formula is satisfiable on a quasimodel.

Theorem (DFD, 2008) DTL *is computably enumerable.*



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Any satisfiable formula may be satisfied over the rational line.

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- Equal to $DTL + \exists \blacksquare p \rightarrow \forall \Diamond p$.
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We will:

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Thank you for your attention!

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